

# Designing Competitive Online Algorithms: **Greediness** and Regret

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# Combinatorial Optimization Problems

Maximization or minimization problems

Algorithm receives an input

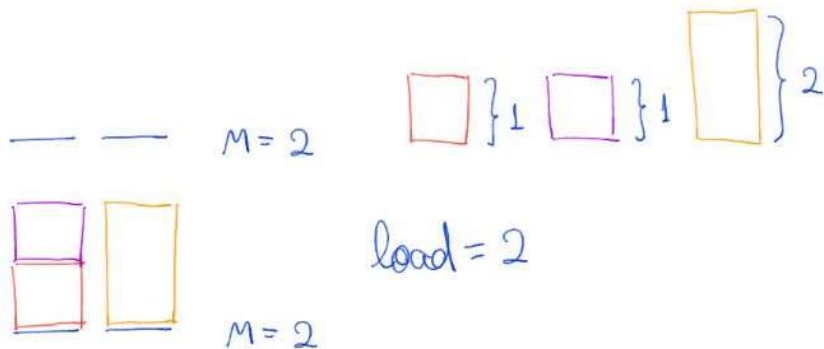
Returns a solution with a cost

As an example, lets take the Load Balancing problem

# Load Balancing problem

Input: machines  $M$ , tasks  $D$ , sizes  $s : D \rightarrow \mathbb{R}^+$

$$l(i) = \sum_{j \in D: a(j)=i} s(j) \quad \min \max_{i=1}^M l(i)$$



# Online Problems

Input parts arrive one at a time

Each part is served before next one arrives

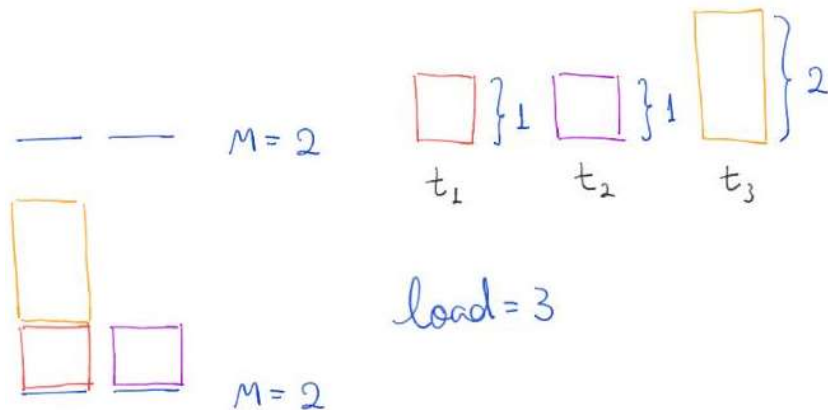
No decision can be changed in the future

As an example, lets take the Online Load Balancing (OLB) problem

# Online Load Balancing problem

Items arrive one at a time

$$\min \max_{i=1}^M l(i)$$



# Competitive Analysis

Worst case analysis technique

For online algorithm ALG

Using offline optimal solution OPT

ALG is  $c$ -competitive if

$$\text{ALG}(I) \leq c \text{OPT}(I)$$

for every input  $I$

As an example, lets take a greedy online algorithm for the OLB

# Greedy Online Load Balancing Algorithm

Always choose the machine with minimum load

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## Algorithm 1: OLB Algorithm

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**Input:**  $M$

For each machine  $i = 1, \dots, M$  set its load  $l(i)$  to 0;

$i^* \leftarrow 1$ ;

**while** a new task  $j$  arrives **do**

$a(j) \leftarrow i^*$ ;

$l(i^*) \leftarrow l(i^*) + s(j)$ ;

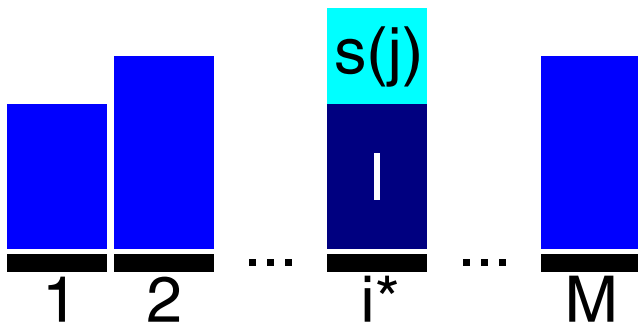
    choose machine with minimum load as new  $i^*$ ;

**return**  $a$ ;

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# Analyzing Greedy Algorithm

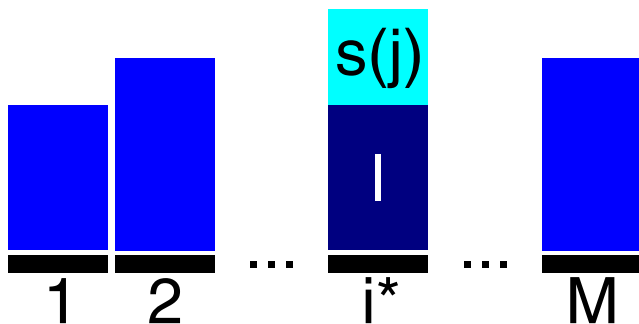
Let  $i^*$  be the machine with maximum load,  $j$  be the last task assigned to  $i^*$ , and  $l(i^*) = l + s(j)$



The idea is to upper bound  $s(j)$  and  $l$  using OPT



# Auxiliary Results



Lemma 1:  $\text{OPT} \geq \max_{j' \in D} s(j') \geq s(j)$

Lemma 2:  $\text{OPT} \geq \frac{1}{M} \sum_{j' \in D} s(j') \geq \frac{1}{M} \sum_{j'=1}^j s(j')$   
 $= \frac{1}{M} \sum_{j'=1}^{j-1} s(j') + \frac{s(j)}{M} \geq I + \frac{s(j)}{M}$

# Greedy Algorithm is $\left(2 - \frac{1}{M}\right)$ -competitive

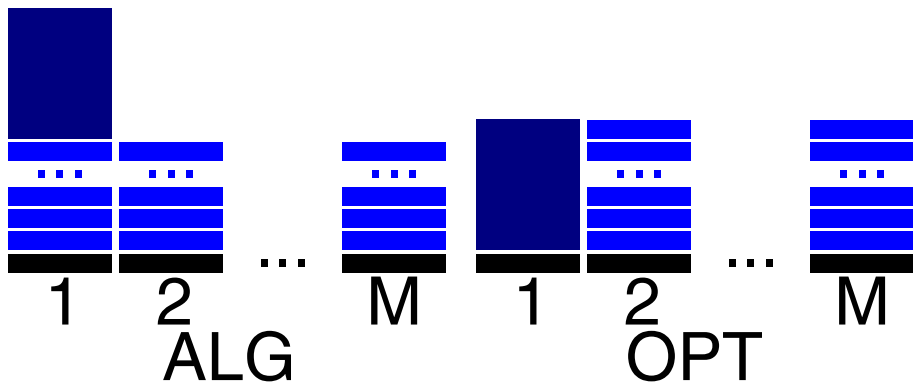
Since  $\text{OPT} \geq s(j)$  and  $\text{OPT} \geq l + \frac{s(j)}{M}$ , we have

$$\begin{aligned}\text{ALG} &= l + s(j) \\ &\leq \text{OPT} - \frac{s(j)}{M} + s(j) \\ &\leq \text{OPT} + \left(1 - \frac{1}{M}\right) \text{OPT} \\ &= \left(2 - \frac{1}{M}\right) \text{OPT}\end{aligned}$$

Thus, the greedy algorithm is 2-competitive

# Lower Bound for Greedy Algorithm

List with  $M(M - 1)$  size 1 tasks followed by one size  $M$  task



We have  $ALG = 2M - 1$  and  $OPT = M$ ,

- i.e.,  $\frac{ALG}{OPT} = \frac{2M-1}{M} = 2 - \frac{1}{M}$

## Two Interesting Special Cases

Since  $\text{OPT} \geq s(j)$  and  $\text{OPT} \geq l + \frac{s(j)}{M}$ , we have

$$\text{ALG} = l + s(j) \leq \left(2 - \frac{1}{M}\right) \text{OPT}$$

Few machines special case: If  $M = 2$  then ALG is  $\frac{3}{2}$ -competitive

Small items special case: If all items are smaller than  $\alpha \text{OPT}$  then

$$\text{ALG} = l + s(j) \leq (1 + \alpha) \text{OPT}$$

# Areas of Interest

Online problems capture uncertainty over time

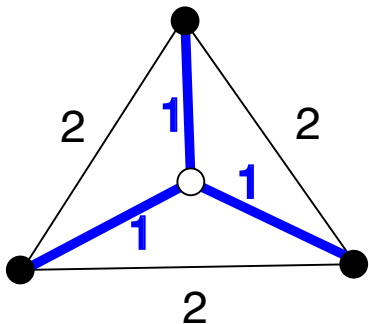
Common in operations research and computer science:

- Resource management: scheduling, packing, load balancing
- Dynamic data structures: list access problem
- Memory management: paging problem
- Sustainability: ski-rental problem
- Network design: Steiner tree, facility location

Greedy is a natural approach, since you are necessarily myopic

# Steiner Tree Problem

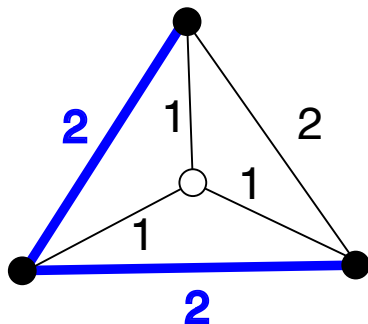
Input:  $G = (V, E)$ ,  $d : E \rightarrow \mathbb{R}^+$ , terminals  $D \subseteq V$



$$\min \sum_{e \in T} d(e) = 3$$

# Online Steiner Tree Problem

Terminal nodes arrive one at a time



$$\min \sum_{e \in T} d(e) = 2 + 2 = 4$$

We are focusing on the metric completion special case.

- Why is this without loss of generality?

# Greedy Online Steiner Tree Algorithm

Connects the current terminal to the closest terminal

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## Algorithm 2: OST Algorithm

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**Input:**  $(G, d)$

$T \leftarrow (\emptyset, \emptyset);$

**while** a new terminal  $j$  arrives **do**

  |  $T \leftarrow T \cup \{(j, V(T))\};$

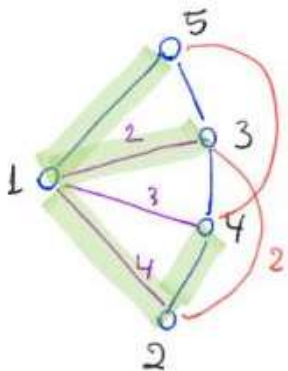
**return**  $T;$

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# Lower Bound for Greedy Algorithm

Lets design a worst case example for the greedy algorithm.



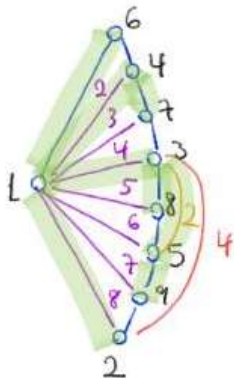
$$OPT = 4$$

$$ALG = 4 + 2 + 2 * 1 = 8$$

$$OPT + \frac{OPT}{2} + \frac{OPT}{2}$$
$$\frac{OPT}{2} * \lg m$$

# Lower Bound for Greedy Algorithm

Generalizing this worst case on a larger graph.



$$\text{OPT} = 8$$

$$\text{ALG} = 8 + 4 + 2 * 2 + 4 * 1 = 20$$

$$\frac{\text{OPT}}{2} + \frac{\text{OPT}}{2} + \frac{\text{OPT}}{2} + \frac{\text{OPT}}{2}$$
$$\underbrace{\hspace{10em}}_{\frac{\text{OPT}}{2} * \lg n}$$

# Greedy Algorithm is $(2 \ln k)$ -competitive

Lemma 1: The  $i$ -th most expensive edge costs at most  $\frac{2\text{OPT}}{i}$

Using Lemma 1, we can prove the main result

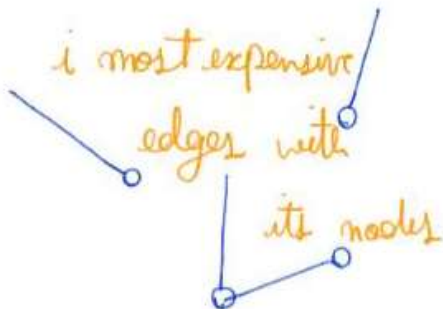
$$\begin{aligned}\text{ALG} &\leq 2\text{OPT} + \text{OPT} + \frac{2}{3}\text{OPT} + \dots \\ &= \sum_{i=1}^{k-1} \frac{2\text{OPT}}{i} \\ &= 2\text{OPT} \sum_{i=1}^{k-1} \frac{1}{i} \\ &= 2\text{OPT} H_{k-1} \\ &\leq 2 \ln k \text{OPT}\end{aligned}$$

# Proving Auxiliary Result

Lemma 1: The  $i$ -th most expensive edge costs at most  $\frac{2OPT}{i}$

Associate each edge with the vertex it connected to the tree

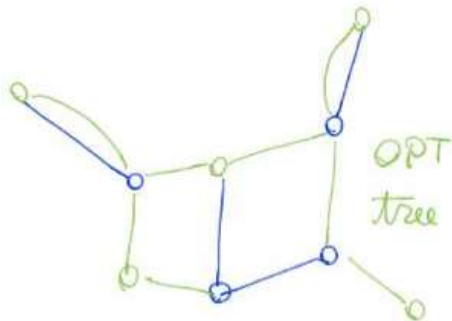
Take a set with the  $i$  “most expensive” vertices



# Proving Auxiliary Result

Lemma 1: The  $i$ -th most expensive edge costs at most  $\frac{2OPT}{i}$

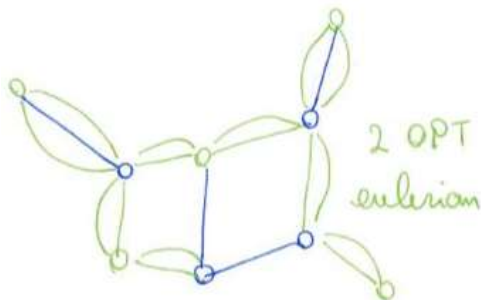
Consider the optimal tree which connects every terminal



# Proving Auxiliary Result

Lemma 1: The  $i$ -th most expensive edge costs at most  $\frac{2OPT}{i}$

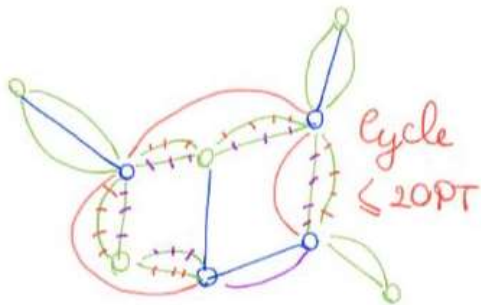
Two optimal trees form an eulerian graph



# Proving Auxiliary Result

Lemma 1: The  $i$ -th most expensive edge costs at most  $\frac{2OPT}{i}$

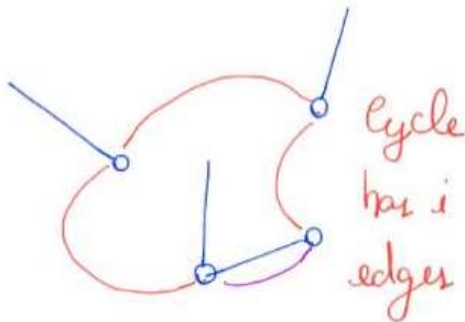
Since we are in the metric completion special case, 2 optimal trees pay for a cycle connecting these vertices



# Proving Auxiliary Result

Lemma 1: The  $i$ -th most expensive edge costs at most  $\frac{2OPT}{i}$

Since the cycle has  $i$  vertices, it has  $i$  edges



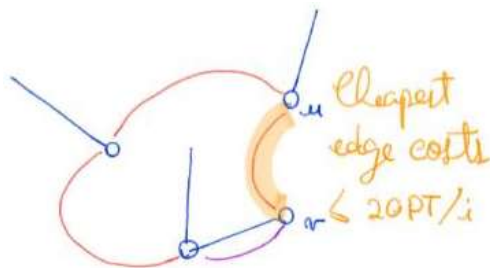


# Proving Auxiliary Result

Lemma 1: The  $i$ -th most expensive edge costs at most  $\frac{2OPT}{i}$

Thus, the average edge cost in this cycle is at most  $\frac{2OPT}{i}$

The cost of the cheapest edge in the cycle is at most the average



# Proving Auxiliary Result

Lemma 1: The  $i$ -th most expensive edge costs at most  $\frac{2\text{OPT}}{i}$

Now we show that, the cheapest edge was an option for the algorithm

Consider both endpoints  $u$  and  $v$  of the cheapest edge

Suppose  $v$  arrived later, at a time  $u$  was already in the algorithm tree

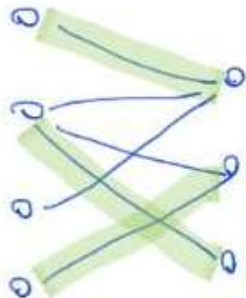
Thus, the greedy algorithm bought an edge with cost at most  $c(u, v)$  to connect  $v$

This bought edge is in the set of the  $i$  most expensive edges

So, the  $i$ -th most expensive edge cost is at most  $c(u, v) \leq \frac{2\text{OPT}}{i}$



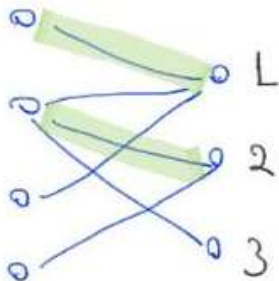
# Bipartite Matching Problem



# Online Bipartite Matching Problem

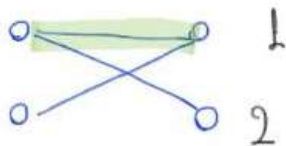
## Greedy Online Bipartite Matching Algorithm

- Connects current r.h.s. node with arbitrary l.h.s. neighbor



# Lower Bound for Online Bipartite Matching

Lets design a worst case example for any deterministic algorithm.



Any deterministic alg.  
is at most  $\frac{1}{2}$ -comp.

# Analyzing Greedy Algorithm

Relying on Linear Programming

$$\begin{aligned} & \max \sum_{e \in E} x_e \\ \text{s.t.} \quad & \sum_{e \in \delta(v)} x_e \leq 1, \forall v \in V \\ & x_e \geq 0, \forall e \in E \end{aligned}$$

and Duality

$$\begin{aligned} & \min \sum_{v \in V} y_v \\ \text{s.t.} \quad & y_u + y_v \geq 1, \forall e = (u, v) \in E \\ & y_u \geq 0, \forall u \in V \end{aligned}$$

For each chosen edge  $e = (u, v)$ , make  $x_e = 1$  and  $y_u = y_v = 1$ .

# Auxiliary Results

For each chosen edge  $e = (u, v)$ , make  $x_e = 1$  and  $y_u = y_v = 1$ .

Idea is based on Primal-Dual relation, in which each constraint corresponds to a variable

Lemma 1:  $\sum_{v \in V} y_v = 2 \sum_{e \in E} x_e$ , since each edge has 2 vertices and no vertex has more than an edge in a matching

Lemma 2: The dual is feasible, i.e.,  $y_u + y_v \geq 1, \forall (u, v) \in E$

By contradiction, suppose there is an edge  $e = (u, v)$  such that  $y_u + y_v = 0$

Since both  $u$  and  $v$  are free, why the algorithm did not chose  $e$  when it arrived?



# Greedy Algorithm is $\frac{1}{2}$ -competitive

Lemma 1:  $\sum_{v \in V} y_v = 2 \sum_{e \in E} x_e$

Lemma 2: The dual is feasible, i.e.,  $y_u + y_v \geq 1, \forall (u, v) \in E$

Back to the main result, since our primal is a maximization problem,

- by weak duality we have  $\text{OPT} \leq \sum_{u \in V} y_u$

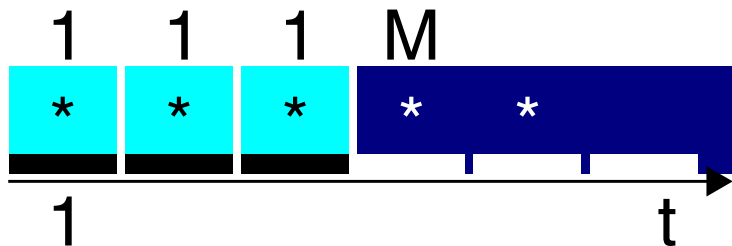
Thus,

$$\begin{aligned} |M| &= \sum_{e \in E} x_e \\ &= \frac{1}{2} \sum_{u \in V} y_u \\ &\geq \frac{1}{2} \text{OPT} \end{aligned}$$

and the greedy algorithm is  $\frac{1}{2}$ -competitive

# Ski Rental Problem

Input: time horizon, skis buying price  $M$  (renting cost is 1 per day), list informing when snow melts



minimize sum of renting days plus  $M$  (if we decide to buy skis)

Does a greedy algorithm solve this problem?

# Ski Rental Application and Generalization

Ski rental algorithms are useful to save energy

Help to decide when to turn off parts of a system

Like cores in a processor or computers in a cluster

Generalized into Parking Permit Problem [Meyerson 2005]

Important both to theoretical and practical leasing problems